

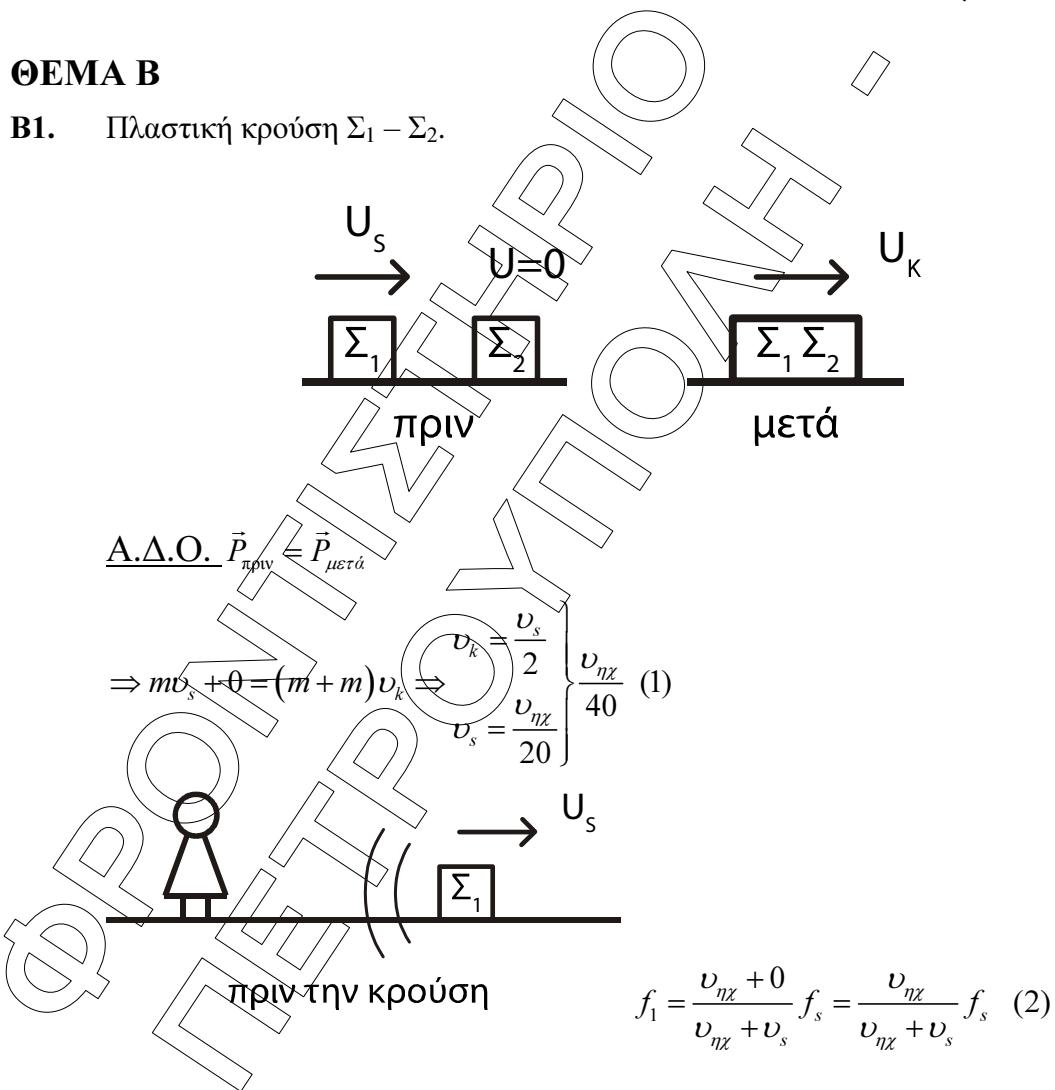
ΦΥΣΙΚΗ
ΠΡΟΣΑΝΑΤΟΛΙΣΜΟΥ
12 ΙΟΥΝΙΟΥ 2019
ΑΠΑΝΤΗΣΕΙΣ

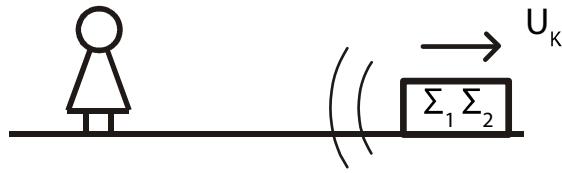
ΘΕΜΑ Α

- A1. β
- A2. γ
- A3. α
- A4. γ
- A5. $\alpha) \rightarrow \Lambda, \quad \beta) \rightarrow \Sigma, \quad \gamma) \rightarrow \Lambda, \quad \delta) \rightarrow \Sigma, \quad \varepsilon) \rightarrow \Sigma$

ΘΕΜΑ Β

- B1. Πλαστική κρούση $\Sigma_1 - \Sigma_2$.





μετά την κρούση

$$f_2 = \frac{v_{\eta\chi}}{v_{\eta\chi} + v_k} f_s = \frac{v_{\eta\chi}}{v_{\eta\chi} + v_s} f_s \quad (3)$$

$$\text{Από } \frac{(2)}{(3)} \Rightarrow \frac{f_1}{f_2} = \frac{\frac{v_{\eta\chi} + v_s}{v_{\eta\chi}} f_s}{\frac{v_{\eta\chi}}{v_{\eta\chi} + v_k} f_s} = \frac{v_{\eta\chi} + v_k}{v_{\eta\chi} + v_s} = \\ = \frac{v_{\eta\chi} + \frac{v_{\eta\chi}}{40}}{v_{\eta\chi} + \frac{v_{\eta\chi}}{20}} = \frac{\frac{41}{40}}{\frac{21}{20}} = \frac{41}{42}$$

Άρα σωστό το (ii)

B2. Εξ. συνέχ. Από $\Delta \rightarrow \Gamma$

$$\Pi_1 = \Pi_2 \Rightarrow A_1 v_1 = A_2 v_2 \Rightarrow 2A_2 \cdot v_1 = A_2 v_2 \Rightarrow v_2 = 2v_1 \quad (1)$$

Bernoulli: $\Delta \rightarrow \Gamma$

$$P_\Delta + \frac{1}{2} \rho v_1^2 = P_2 + \frac{1}{2} \rho v_2^2$$

Στον κατακόρυφο σωλήνα $\Rightarrow P_{atm} + \rho gh + \frac{1}{2} \rho v_1^2 = P_{atm} + \frac{1}{2} \rho v_2^2 \Rightarrow$

$$P_\Delta = P_{atm} + \rho gh$$

$$\Rightarrow gh + \frac{1}{2} v_1^2 = \frac{1}{2} v_2^2 \stackrel{(1)}{\Rightarrow} gh + \frac{1}{2} \frac{v_2^2}{4} = \frac{1}{2} v_2^2 \Rightarrow$$

$$\Rightarrow \frac{3}{8} v_2^2 = gh \Rightarrow v = \sqrt{\frac{8}{3} gh} \quad (2)$$

Στο δοχείο η επιφάνεια σταθερή σε ύψος (H) $\left. \begin{array}{l} \Pi_2 = \Pi_3 \\ A_2 v_2 = A_3 v_3 \end{array} \right\} \Rightarrow A_2 v_2 = A_3 v_3 \Rightarrow$

$$\Rightarrow A_2 v_2 = \frac{A_2}{2} v_3 \Rightarrow v_3 = 2v_2$$

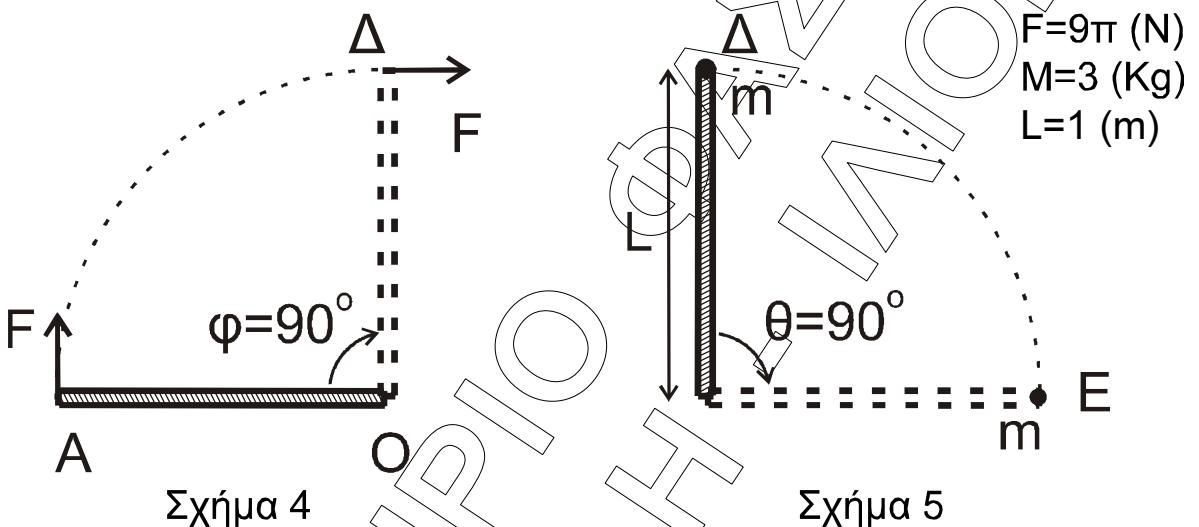
Bernoulli: E → Z

$$P_{\text{atm}} + \rho g H + 0 = P_{\text{atm}} + \frac{1}{2} \rho v_3^2 + 0 \Rightarrow gH = \frac{1}{2} 4v_2^2 \Rightarrow$$

$$\Rightarrow gH = 2v_2^2 \Rightarrow v_2 = \sqrt{g \frac{H}{2}} \quad \text{από την (2)} \Rightarrow \sqrt{\frac{8}{3} gh} = \sqrt{g \frac{H}{2}} \Rightarrow \frac{h}{H} = \frac{3}{16}$$

Σωστό (iii)

B3.



Για την κίνηση $A \rightarrow \Delta$ από το Θ.Μ.Κ.Ε. ισχύει:

$$\Delta K = \Sigma W \Rightarrow \frac{1}{2} \cdot I_O \cdot \omega_A^2 = (F \cdot L) \frac{\pi}{2} \Rightarrow \frac{1}{2} \cdot \frac{1}{3} \cdot M \cdot L^2 \cdot \omega_A^2 = F \cdot L \cdot \frac{\pi}{2} \Rightarrow \\ \Rightarrow \frac{1}{2} \cdot \frac{1}{3} \cdot 3 \cdot 1 \cdot \omega_A^2 = 9\pi \cdot 1 \cdot \frac{\pi}{2} \Rightarrow \omega_A = 3\pi \text{ rad/s}$$

Από Α.Δ.Σ. στην κρούση στο (Δ) ισχύει:

$$\vec{L}_{\mu \nu \tau \alpha} = \vec{L}_{\mu \nu \tau \alpha} \Rightarrow I'_O \cdot \omega_A = I'_O \cdot \omega_\Delta \Rightarrow \omega_\Delta = \frac{I_O}{I'_O} \omega_A \quad (1)$$

$$\text{Όμως } I'_O = \frac{1}{3} M \cdot L^2 + mL^2 = \frac{3 \cdot 1^2}{3} + 1 \cdot 1^2 = 2 \text{ Kgm}^2 \quad (2)$$

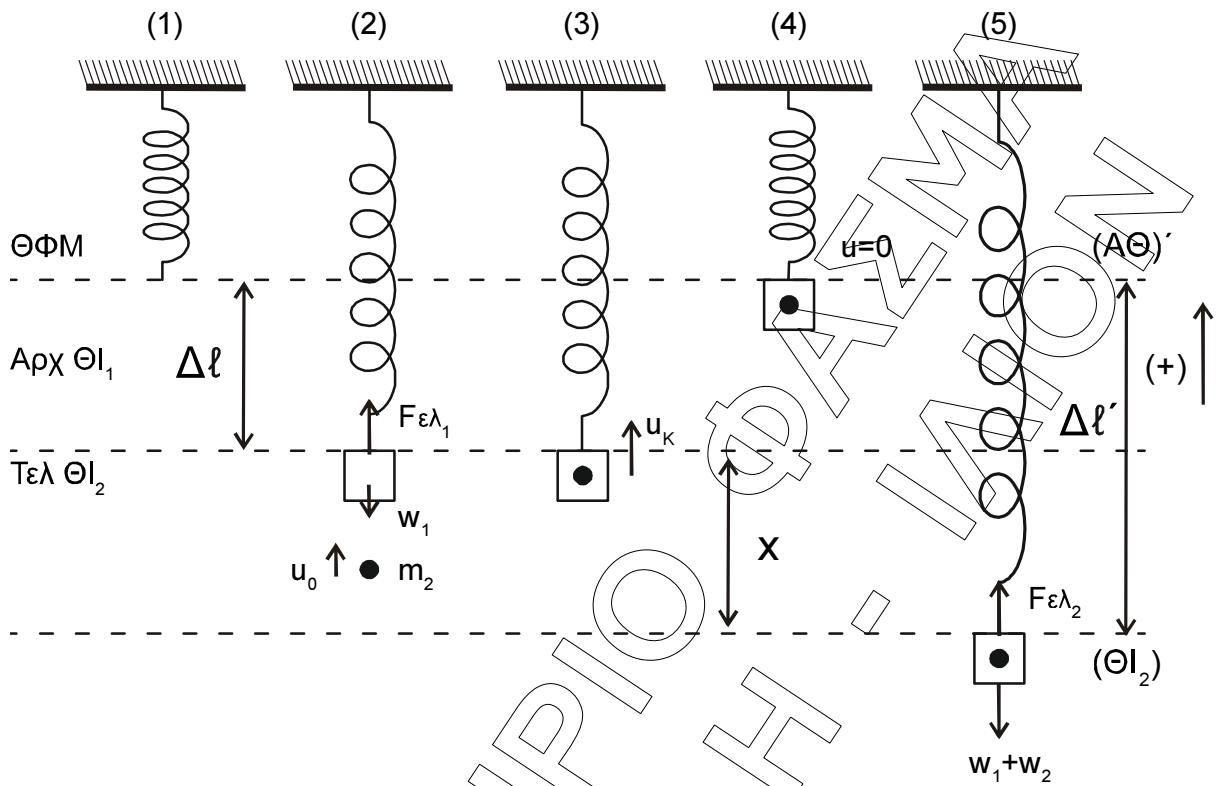
$$\text{Από (1) και (2) έχουμε: } \omega_\Delta = \frac{ML^2}{3} \cdot \omega_A = \frac{3 \cdot 1}{3} \cdot 3\pi = \frac{3\pi}{2} \text{ rad/s}$$

Για τον χρόνο $t_{\Delta \rightarrow E} = t$ έχουμε

$$\Delta \Theta = \omega'_\Delta \cdot t \Rightarrow \frac{\pi}{2} = \frac{3\pi}{2} \cdot t \Rightarrow t = \frac{1}{3} \text{ (s)}$$

Άρα σωστό είναι το (ii).

ΘΕΜΑ Γ



Γ1. Για την αρχική Θ.Ι₁ σχήμα (2) λογάρισμοι:

$$\Sigma F_y = 0 \Rightarrow W_1 = F_{\varepsilon\lambda,1} \Rightarrow m_1 \cdot g = K \cdot \Delta l \Rightarrow K = \frac{10}{0,05} = 200 \text{ N/m}$$

Για την τελική ΘΙ₂, σχήμα (3)

$$\Sigma F_y = 0 \Rightarrow W_1 + W_2 = F_{\varepsilon\lambda,2} \Rightarrow (m_1 + m_2) \cdot g = K \cdot \Delta l' \Rightarrow 20 = 200 \cdot \Delta l' \Rightarrow \Delta l' = 0,1 \text{ m}$$

Αρα το πλάτος ΑΘ', ΘΙ₂: $\Delta l' - \Delta l = A = 0,1 \text{ m}$

Γ2. $x = \Delta l' - \Delta l = 0,05 \text{ m}$

ΑΔΕΤ:

$$K + U = E_T \Rightarrow \frac{1}{2} \cdot (m_1 + m_2) \cdot v_K^2 + \frac{1}{2} \cdot k \cdot x^2 = \frac{1}{2} \cdot k \cdot A^2 \Rightarrow 2 \cdot v_K^2 + 200 \cdot 0,05^2 = 200 \cdot 0,1^2 \Rightarrow v_K^2 = 1 - 0,25 \Rightarrow v_K = \sqrt{0,75} = \frac{\sqrt{3}}{2} \text{ m/s}$$

$$\text{Από: } P_{προ} = P_{μετά} \Rightarrow m \cdot v_o = 2 \cdot m \cdot v_K \Rightarrow v_o = \frac{\sqrt{3}}{2} \cdot 2 = \sqrt{3} \text{ m/s}$$

$$\text{Αρα } K = \frac{1}{2} \cdot m \cdot v_o^2 = \frac{1}{2} \cdot 1 \cdot \sqrt{3}^2 = \frac{3}{2} = 1,5 \text{ J}$$

Γ3.

$$\begin{aligned}\Delta \vec{P}_2 &= \vec{P}'_2 - \vec{P}_2 = \Delta P_2 = m_2 v_k - m_2 v_0 \Rightarrow \\ \Delta P_2 &= \frac{\sqrt{3}}{2} - \sqrt{3} \Rightarrow \Delta P_2 = -\frac{\sqrt{3}}{2} \text{ kg m/s} \Rightarrow \\ \Rightarrow |\Delta P_2| &= \frac{\sqrt{3}}{2} \text{ kg m/s}\end{aligned}$$

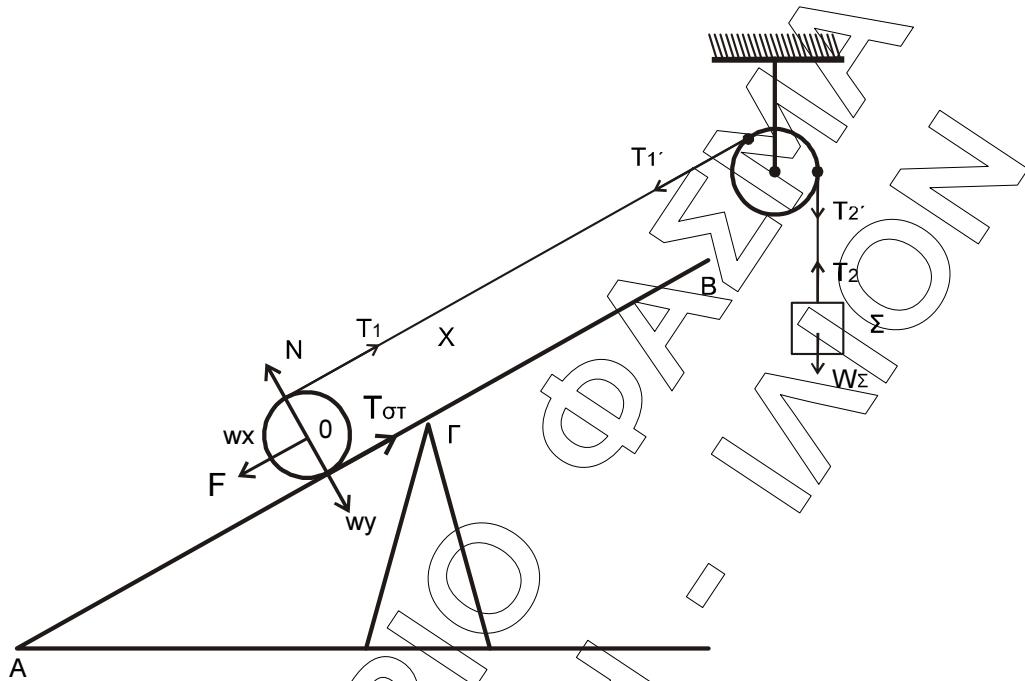
Με κατεύθυνση προς τα κάτω, προς τα αρνητικά.

Γ4. Για $t = 0$, $x = 0,05\text{m}$, $A = 0,1 \text{ m}$, $v > 0$

$$\begin{aligned}x = A\eta\mu(\omega t + \varphi_0) \stackrel{t=0}{\Rightarrow} 0,05 = 0,1 \eta\mu\varphi_0 \Rightarrow \eta\mu\varphi_0 = \frac{1}{2} = \eta\mu \frac{\pi}{6} \\ \text{άρα } \varphi_0 = 2\kappa\pi + \frac{\pi}{6} \\ \text{ή } \varphi_0 = 2\kappa\pi + \frac{5\pi}{6} \\ \left. \begin{array}{l} 0 \leq \varphi_0 < 2\pi \\ \kappa = 0 \end{array} \right\} \Rightarrow \\ \varphi_0 = \frac{\pi}{6} \text{ με } v > 0 \text{ δεκτή} \\ \varphi_0 = \frac{5\pi}{6} \quad v < 0 \\ w = \sqrt{\frac{k}{m_1 + m_2}} = \sqrt{100} = 10 \text{ rad/s} \\ \text{Άρα η απομάκρυνση είναι} \\ x = 0,1\eta\mu \left(10t + \frac{\pi}{6} \right) \text{ (SI)}\end{aligned}$$

ΘΕΜΑ Δ

Δ1.



Σώμα (Σ):

$$\begin{aligned} \sum F_y = 0 \Rightarrow T_2 &= W_\Sigma \\ T_2' &= T_2 \end{aligned} \quad \left. \begin{array}{l} T_2' \neq W_\Sigma \Rightarrow T_2' = 20 \text{ N} \\ T_2 = T_2' \end{array} \right\}$$

Στην τροχαλία:

$$\sum \tau_{(K)} = 0 \Rightarrow T_1' R_\Gamma = T_2' R_\Gamma \Rightarrow T_1' = T_2' \Rightarrow T_1' = 20 \text{ N}$$

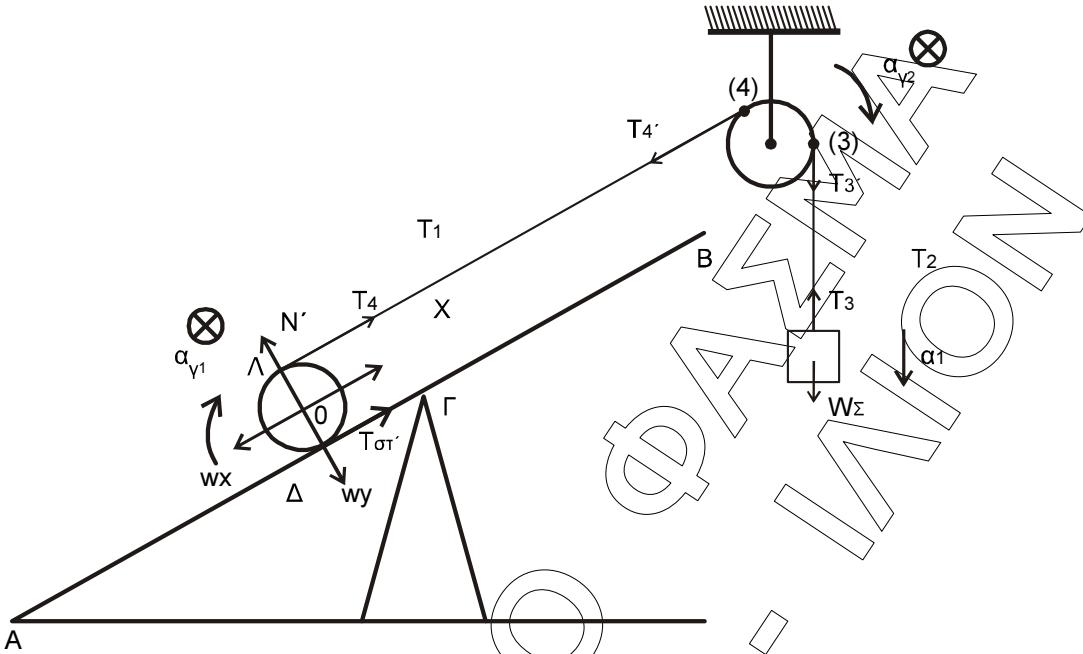
$$T_1 = T_1' = 20 \text{ N}$$

Στον κύλινδρο:

$$\sum \tau_{(0)} = 0 \Rightarrow T_1' R_K = T_{\sigma\tau} R_K \Rightarrow T_{\sigma\tau} = 20 \text{ N}$$

$$\sum F_x = 0 \Rightarrow F + W_x = T_1 + T_{\sigma\tau} \Rightarrow F = 40 - 10 \Rightarrow F = 30 \text{ N}$$

Δ2.



Για τον κύλινδρο $T_3 = T'_3$, $T_4 = T'_4$ αβαρή νήματα
μεταφ: $\Sigma F_x = m_k \cdot a_{cm} \Rightarrow T_4 + T'_{\sigma\tau} - W_x = m_k \cdot a_{cm}$ (1)

στροφ: $\Sigma \tau_{(0)} = I_0 \cdot \alpha_{\gamma_1} \Rightarrow T_4 \cdot R_k - T'_{\sigma\tau} \cdot R_k = m_k \frac{R_k^2}{2} \alpha_{\gamma_1}$ (2)

Στην τροχαλία:

στροφ: $\Sigma \tau_k = I_k \cdot \alpha_{\gamma_2} \Rightarrow T'_4 \cdot R_T - T'_3 \cdot R_T = m_T \frac{R_T^2}{2} \alpha_{\gamma_2}$ (3)

Στο σώμα:

μεταφ: $\Sigma F_y = m_\Sigma \cdot a \Rightarrow W_\Sigma - T_3 = m_\Sigma \cdot a$ (4)

η ταχύτητα των σώματος $v_\Sigma = v_3$ άρα $\alpha_2 = \alpha \Rightarrow \alpha = \alpha_{\gamma_2} R_T$ (5)

η ταχύτητα $v_\Lambda = v_4$ άρα $\alpha_A = \alpha_4 = \alpha_{\gamma_2} \cdot R_T$

όμως $v_\Lambda = 2v_{cm}$ άρα $\alpha_A = 2\alpha_{cm}$

$v_\Delta = 0$ άρα $v_{cm} = \omega \cdot R_k$ άρα $\alpha_{cm} = a_{\gamma_1} R_k$ (7)

$2\alpha_{cm} = \alpha$ (6)

Δύνοντας:

$$\text{Από (2), (7)} \Rightarrow (T'_4 - T'_{\sigma\tau}) R_k = \frac{m_k R_k^2}{2} \alpha_{cm} \Rightarrow T'_4 - T_{\sigma\tau} = \frac{m_k}{2} \alpha_{cm} \stackrel{(m_k=2)}{\Rightarrow} T'_4 - T_{\sigma\tau} = \alpha_{cm} \quad (8)$$

$$\text{Από (3), (5)} \Rightarrow (T'_3 - T'_4) R_T = \frac{m_T R_T^2}{2} \alpha \Rightarrow T'_3 - T'_4 = \frac{m_T}{2} \alpha \stackrel{(m_T=2)}{\Rightarrow} T_3 - T_4 = \alpha \quad (9)$$

$$\text{Από (8), (6)} \Rightarrow T_4 - T_{\sigma\tau} = \frac{\alpha}{2} \quad (10)$$

$$\begin{cases} (4) & 20 - T_3 = 2\alpha \\ (9) & T_3 - T_4 = \alpha \end{cases} \Rightarrow 20 - T_4 = 3\alpha \quad (11)$$

$$\Delta\pi\delta(1)(6) \Rightarrow T_4 + T_{\sigma\tau} - m_k g \eta \mu \varphi = m_k \cdot a_{cm}$$

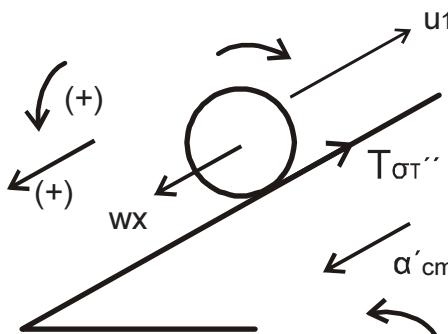
$$T_4 + T_{\sigma\tau} - 2 \cdot 10 \frac{1}{2} = 2 \frac{a}{2} \Rightarrow T_4 - T_{\sigma\tau} = 10 + a \quad (12)$$

$$\Delta\pi\delta(10), (12) \Rightarrow 2T_4 = 10 + \frac{3a}{2} \Rightarrow$$

$$2(20 - 3a) = 10 + \frac{3a}{2} \Rightarrow 40 - 6a = 10 + \frac{3a}{2} \Rightarrow a = 4 \text{ m/s}^2$$

$$(6) \quad a_{cm} = \frac{\alpha}{2} = 2 \text{ m/s}^2.$$

Δ3.



$$v_1 = a_1 \cdot t = 2 \cdot 0,5 = 1 \text{ m/s}$$

$$\Sigma F_x = M \cdot a_{cm}$$

$$W_x - Ts'' = M_K \cdot a_{cm}'$$

$$M_K \cdot g \cdot \eta \mu \varphi - Ts'' = M_K \cdot a_{cm}' \quad (1)$$

$$\Sigma \tau = I_K \cdot \alpha'_{\gamma\omega v} \Rightarrow Ts'' \cdot R_K = \frac{M_K R_K^2}{2} \cdot \alpha'_{\gamma\omega v} \quad (2)$$

$$\text{κύλιση } a'_{cm} = \alpha'_{\gamma\omega v} \cdot R_K \quad (3)$$

$$\text{Από (2) κατ (3)} \quad Ts'' \cdot R_K = M_K \frac{R_K^2}{2} \cdot \frac{a'_{cm}}{R_K} \Rightarrow Ts'' = \frac{M_K \cdot a'_{cm}}{2} = \frac{2 \cdot a'_{cm}}{2} \Rightarrow$$

$$\Rightarrow Ts'' = a'_{cm} \quad (4)$$

$$(1) \cdot (4) \quad 2 \cdot 10 \cdot \frac{1}{2} \cdot a'_{cm} = 2a'_{cm} \Rightarrow 10 = 3a'_{cm} \Rightarrow$$

$$\Rightarrow a'_{cm} = \frac{10}{3} \text{ m/s}^2$$

$$v = v_1 - a_{cm} \cdot \Delta t \Rightarrow 0 = 1 - \frac{10}{3} \cdot \Delta t \Rightarrow \Delta t = \frac{3}{10} = 0,3 \text{ s}$$

$$t_{STOP} = 0,5 + \Delta t = 0,8 \text{ s}$$

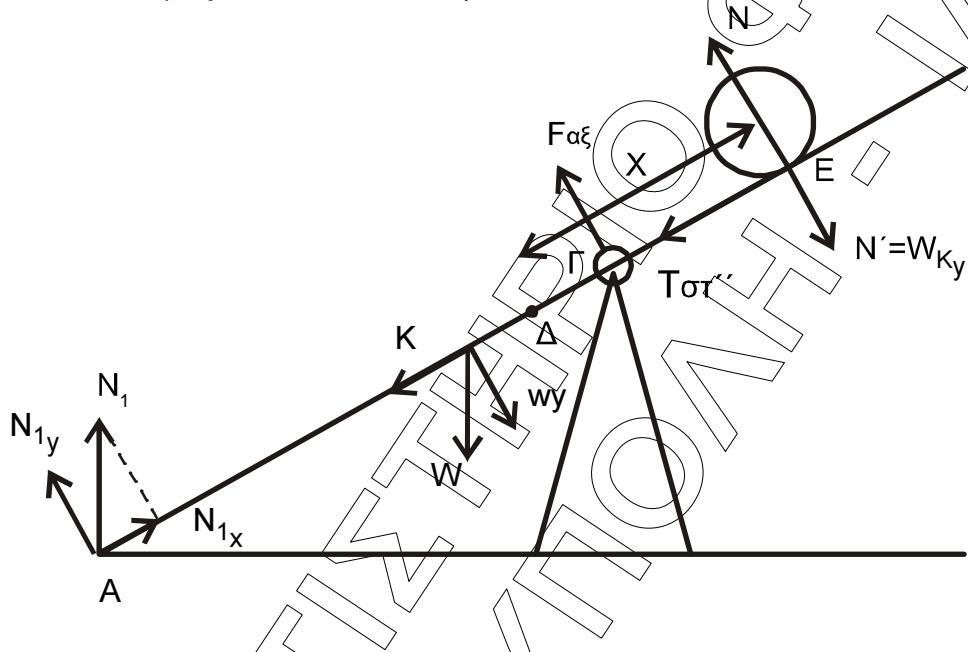
Δ4.

$$S_{OA} = S_1 + S_2$$

$$S_1 = \frac{1}{2} \alpha_1 t_1^2 = \frac{1}{2} \cdot 2 \cdot 0,5^2 = 0,25 \text{ m}$$

$$\begin{aligned} S_2 &= v_1 \cdot \Delta t - \frac{1}{2} \cdot \alpha_{\text{cm}} \cdot \Delta t^2 = 1 \cdot 0,3 - \frac{1}{2} \cdot \frac{10}{3} \cdot 0,3^2 = \\ &= 0,3 - \frac{1}{2} \cdot \frac{10}{3} \cdot 0,3 \cdot 0,3 = 0,3 - \frac{1}{2} \cdot 0,3 = 0,15 \text{ m} \\ S_{OA} &= 0,25 + 0,15 = 0,4 \text{ m} \end{aligned}$$

Δ5. Οι δυνάμεις που ασκούνται στην σανίδα



$$\begin{aligned} \sum \tau_{(\Gamma)} &= 0 \Rightarrow W_y(K\Gamma) - N_{1y}(A\Gamma) - W_{K_y}(\Gamma E) = 0 \Rightarrow \\ &\Rightarrow M g \cdot \sigma u v \varphi(K\Gamma) - M_K \cdot g \cdot \sigma u v \varphi(\Gamma E) = N_1 \cdot \sigma u v \varphi(A\Gamma) \Rightarrow \\ &\Rightarrow 20 \cdot 0,5 - 20 \cdot 0,2 = N_1 \cdot 2,5 \Rightarrow N_1 = \frac{6}{2,5} = 2,4 \text{ N} \end{aligned}$$

Εναλλακτικά

$$\begin{aligned} \sum \tau_{(\Gamma)} &= 0 \Rightarrow W_y(K\Gamma) - N_{1y}(A\Gamma) - W_{K_y}(x - \Gamma\Delta) = 0 \Rightarrow \\ &\Rightarrow M g \cdot \sigma u v \varphi(K\Gamma) - M_K \cdot g \cdot \sigma u v \varphi(x - \Gamma\Delta) = N_1 \cdot \sigma u v \varphi(A\Gamma) \Rightarrow \\ &\Rightarrow 20 \cdot 0,5 - 20 \cdot (x - 0,2) = N_1 \cdot 2,5 \Rightarrow 10 - 20x + 4 = N_1 \cdot 2,5 \Rightarrow \\ &\Rightarrow 14 - 20x = 2,5N_1 \Rightarrow N_1 = 5,6 = 8x \end{aligned}$$

$$\text{Η πρέπει } N_1 \geq 0 \Rightarrow 5,6 - 8x \geq 0 \Rightarrow x \leq 0,7 \text{ m}$$

$0 \leq x \leq 0,4 \text{ m}$ áρα δεν ανατρέπεται.